# **8-Input Priority Encoder**

The MC10165 is a device designed to encode eight inputs to a binary coded output. The output code is that of the highest order input. Any input of lower priority is ignored. Each output incorporates a latch allowing synchronous operation. When the clock is low the outputs follow the inputs and latch when the clock goes high. This device is very useful for a variety of applications in checking system status in control processors, peripheral controllers, and testing systems.

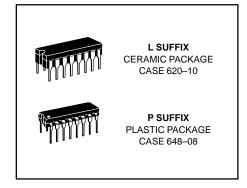
The input is active when high, (e.g., the three binary outputs are low when input D0 is high). The Q3 output is high when any input is high. This allows direct extension into another priority encoder when more than eight inputs are necessary. The MC10165 can also be used to develop binary codes from random logic inputs, for addressing ROMs, RAMs, or for multiplexing data.

 $P_D = 545$  mW typ/pkg (No Load)  $t_{pd} = 4.5$  ns typ (Data to Output)  $t_r$ ,  $t_f = 2.0$  ns typ (20%–80%)

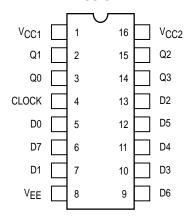
#### **TRUTH TABLE**

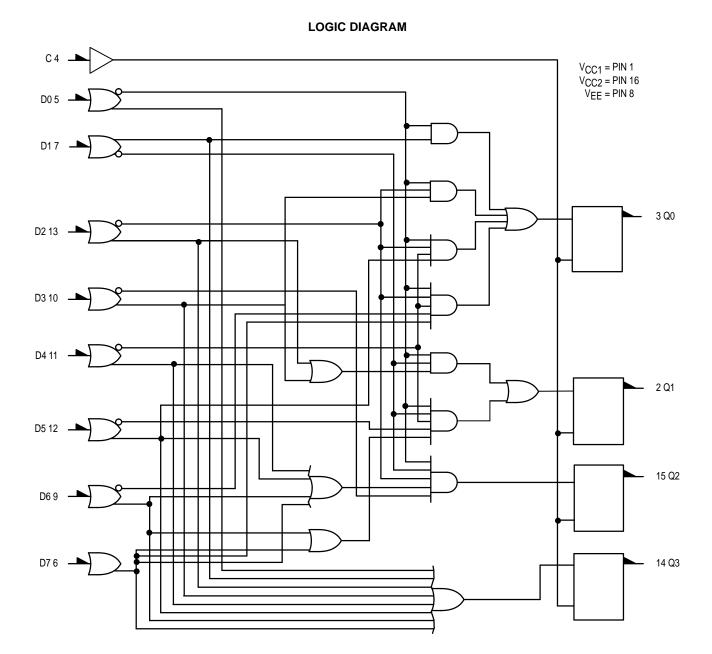
DATA INPUTS								OUTF	PUTS		
D0	D1	D2	D3	D4	D5	D6	D7	Q3	Q2	Q1	Q0
Н	Χ	Χ	Χ	Х	Χ	Х	Χ	Н	L	L	L
L	Н	Х	Χ	Χ	Х	Х	Х	Н	L	L	Н
L	L	Н	Х	Χ	Х	Х	Х	Н	L	Н	L
L	L	L	Н	Χ	Х	Х	Χ	Н	L	Н	Н
L	L	L	L	Н	Х	Х	Х	Н	Н	L	L
L	L	L	L	L	Н	Х	Χ	Н	Н	L	Н
L	L	L	L	L	L	Н	Х	Н	Н	Н	L
L	L	L	L	L	L	L	Н	Н	Н	Н	Н
L	L	L	L	L	L	L	L	L	L	L	L

# MC10165



## **PIN ASSIGNMENT**





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# **ELECTRICAL CHARACTERISTICS**

			Test Limits							
		Pin Under	−30°C		+25°C			+85°C		1
Characteristic	Symbol	Test	Min	Max	Min	Тур	Max	Min	Max	Unit
Power Supply Drain Currer	ΙE	8		144		105	131		144	mAdc
Input Current	l <sub>inH</sub>	4 5		390 350			245 220		245 220	μAdc
	l <sub>inL</sub>	4 5	0.5 0.5		0.5 0.5			0.3 0.3		μAdc
Output Voltage Log	·1 V <sub>OH</sub>	2 3 14 15	-1.060 -1.060 -1.060 -1.060	-0.890 -0.890 -0.890 -0.890	-0.960 -0.960 -0.960 -0.960		-0.810 -0.810 -0.810 -0.810	-0.890 -0.890 -0.890 -0.890	-0.700 -0.700 -0.700 -0.700	Vdc
Output Voltage Log	0 V <sub>OL</sub>	2 3 14 15	-1.890 -1.890 -1.890 -1.890	-1.675 -1.675 -1.675 -1.675	-1.850 -1.850 -1.850 -1.850		-1.650 -1.650 -1.650 -1.650	-1.825 -1.825 -1.825 -1.825	-1.615 -1.615 -1.615 -1.615	Vdc
Threshold Voltage Log	:1 V <sub>OHA</sub>	2 3 14 15	-1.080 -1.080 -1.080 -1.080		-0.980 -0.980 -0.980 -0.980			-0.910 -0.910 -0.910 -0.910		Vdc
Threshold Voltage Log	0 VOLA	2 3 14 15		-1.655 -1.655 -1.655 -1.655			-1.630 -1.630 -1.630 -1.630		-1.595 -1.595 -1.595 -1.595	Vdc
Switching Times (50 $\Omega$ Lo	d)									ns
Propagation Delay Data In	t5+14+ t5-14- t7+3+ t11+15+ t13+2+	14 14 3 15 2	2.0 2.0 2.0 2.0 2.0 2.0	7.0 7.0 7.0 7.0 7.0	3.0 3.0 3.0 3.0 3.0		7.0 7.0 7.0 7.0 7.0	2.0 2.0 2.0 2.0 2.0	8.0 8.0 8.0 8.0	
Clock In	t4-3+ t4-3- t4-14+ t4-14-	3 (2.) 3 (3.) 14 (2.) 14 (3.)	1.5 1.5 1.5 1.5	4.5 4.5 4.5 4.5	2.0 2.0 2.0 2.0		4.0 4.0 4.0 4.0	1.5 1.5 1.5 1.5	4.5 4.5 4.5 4.5	
Setup Time	t <sub>setup</sub> H t <sub>setupL</sub>	3 3	6.0 6.0		6.0 6.0	3.4 3.0		6.0 6.0		
Hold Time	<sup>t</sup> holdH <sup>t</sup> holdL	3 3	1.0 1.0		1.0 1.0	-2.3 -2.7		1.0 1.0		
Rise Time (20 to 80	%) t <sub>3+</sub>	3	1.1	3.5	1.1	2.0	3.3	1.1	3.5	
Fall Time (20 to 80	%) t <sub>3</sub> _	3	1.1	3.5	1.1	2.0	3.3	1.1	3.5	

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The same limit applies for all D type input pins. To test input currents for other D inputs, individually apply proper voltage to pin under test.
 Output latched to low state prior to test.
 Output latched to high state prior to test.
 To preserve reliable performance, the MC10165P (plastic packaged device only) is to be operated in ambient temperatures above 70°C only when 500 lfpm blown air or equivalent heat sinking is provided.

## **ELECTRICAL CHARACTERISTICS** (continued)

				TEST VOLTAGE VALUES (Volts)					
		@ Test Te	mperature	V <sub>IHmax</sub>	V <sub>ILmin</sub>	VIHAmin	VILAmax	VEE	1
			–30°C	-0.890	-1.890	-1.205	-1.500	-5.2	
			+25°C	-0.810	-1.850	-1.105	-1.475	-5.2	
			+85°C	-0.700	-1.825	-1.035	-1.440	-5.2	
			Pin Under	TEST \	OLTAGE A	PPLIED TO	PINS LISTED I	BELOW	(/)
Characteristic		Symbol	Test	V <sub>IHmax</sub>	V <sub>ILmin</sub>	V <sub>IHAmin</sub>	V <sub>ILAmax</sub>	V <sub>EE</sub>	(V <sub>CC</sub> ) Gnd
Power Supply Drain Cu	urrent	ΙΕ	8					8	1, 16
Input Current		l <sub>in</sub> H	4 5	4 5 (1.)				8 8	1, 16 1, 16
		linL	4 5		4 5 (1.)			8 8	1, 16 1, 16
Output Voltage	Logic 1	VOH	2 3 14 15	6 6 6	4 4 4 4			8 8 8 8	1, 16 1, 16 1, 16 1, 16
Output Voltage	Logic 0	VOL	2 3 14 15		4 4 4			8 8 8	1, 16 1, 16 1, 16 1, 16
Threshold Voltage	Logic 1	VOHA	2 3 14 15		4 4 4 4	6 6 6		8 8 8 8	1, 16 1, 16 1, 16 1, 16
Threshold Voltage	Logic 0	V <sub>OLA</sub>	2 3 14 15		4 4 4 4		6 6 6	8 8 8 8	1, 16 1, 16 1, 16 1, 16
Switching Times	(50Ω Load)			+1.11V	+0.31V	Pulse In	Pulse Out	-3.2 V	+2.0
Propagation Delay	Data Input	<sup>t</sup> 5+14+ <sup>t</sup> 5-14- <sup>t</sup> 7+3+ <sup>t</sup> 11+15+ <sup>t</sup> 13+2+	14 14 3 15 2		4 4 4 4 4	5 5 7 11 13	14 14 3 15 2	8 8 8 8	1, 16 1, 16 1, 16 1, 16 1, 16
	Clock Input	t <sub>4-3+</sub> t <sub>4-3-</sub> t <sub>4-14+</sub> t <sub>4-14-</sub>	3 (2.) 3 (3.) 14 (2.) 14 (3.)	7 7		4 4 4 4	3 3 14 14	8 8 8 8	1, 16 1, 16 1, 16 1, 16
Setup Time		<sup>t</sup> setupH <sup>t</sup> setupL	3 3			4,7 4,7	3 3	8 8	1, 16 1, 16
Hold Time		<sup>t</sup> holdH <sup>t</sup> holdL	3 3			4,7 4,7	3 3	8 8	1, 16 1, 16
Rise Time	(20 to 80%)	t3+	3		4	7	3	8	1, 16
Fall Time	(20 to 80%)	t3_	3		4	7	3	8	1, 16

<sup>1.</sup> The same limit applies for all D type input pins. To test input currents for other D inputs, individually apply proper voltage to pin under test.

Each MECL 10,000 series circuit has been designed to meet the dc specifications shown in the test table, after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse air flow greater than 500 linear fpm is maintained. Outputs are terminated through a 50–ohm resistor to –2.0 volts. Test procedures are shown for only one gate. The other gates are tested in the same manner.

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<sup>2.</sup> Output latched to low state prior to test.

<sup>3.</sup> Output latched to high state prior to test.

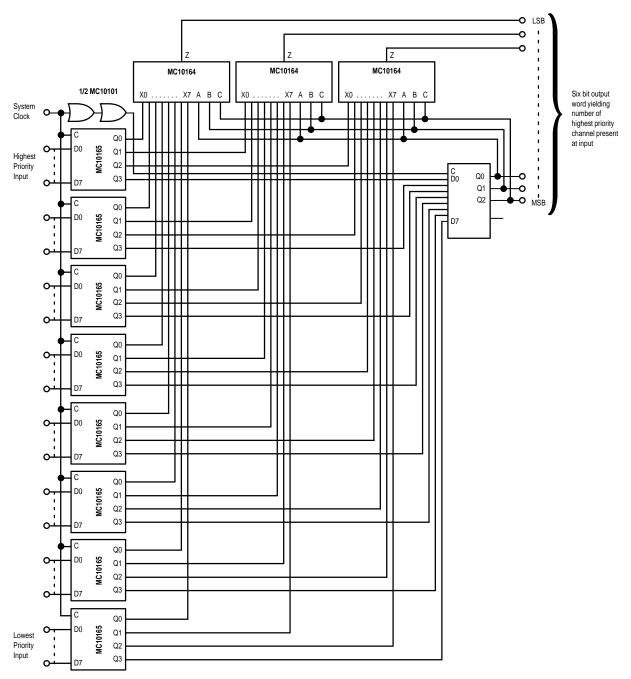
<sup>\*</sup> To preserve reliable performance, the MC10165P (plastic packaged device only) is to be operated in ambient temperatures above 70°C only when 500 lfpm blown air or equivalent heat sinking is provided.

# **APPLICATION INFORMATION**

A typical application of the MC10165 is the decoding of system status on a priority basis. A 64 line priority encoder is shown in the figure below. System status lines are

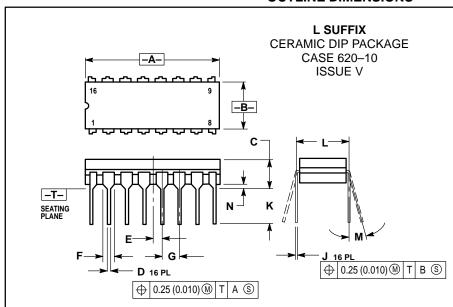
connected to this encoder such that, when a given condition exists, the respective input will be at a logic high level. This scheme will select the one of 64 different system conditions, as represented at the encoder inputs, which has priority in determining the next system operation to be performed. The binary code showing the address of the highest priority input present will appear at the encoder outputs to control other system logic functions.

## **64-LINE PRIORITY ENCODER**



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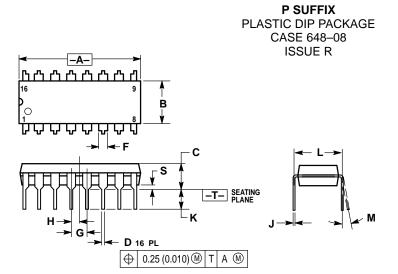
## **OUTLINE DIMENSIONS**



#### NOTES:

- DIMENSIONING AND TOLERANCING PER
- ANSI Y14.5M, 1982. CONTROLLING DIMENSION: INCH.
- DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
- DIMENSION F MAY NARROW TO 0.76 (0.030) WHERE THE LEAD ENTERS THE CERAMIC

	INC	HES	MILLIMETERS			
DIM	MIN	MAX	MIN	MAX		
Α	0.750	0.785	19.05	19.93		
В	0.240	0.295	6.10	7.49		
С		0.200		5.08		
D	0.015	0.020	0.39	0.50		
Е	0.050	BSC	1.27 BSC			
F	0.055	0.065	1.40	1.65		
G	0.100	BSC	2.54 BSC			
Н	0.008	0.015	0.21	0.38		
K	0.125	0.170	3.18	4.31		
L	0.300	BSC	7.62 BSC			
M	0°	15°	0 °	15°		
N	N 0.020 0.040		0.51	1.01		



- NOTES:
  1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982. CONTROLLING DIMENSION: INCH.
- DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL
- DIMENSION B DOES NOT INCLUDE MOLD FLASH.
- ROUNDED CORNERS OPTIONAL

	INC	HES	MILLIMETERS			
DIM	MIN	MAX	MIN	MAX		
Α	0.740	0.770	18.80	19.55		
В	0.250	0.270	6.35	6.85		
С	0.145	0.175	3.69	4.44		
D	0.015	0.021	0.39	0.53		
F	0.040	0.70	1.02	1.77		
G	0.100	BSC	2.54 BSC			
Н	0.050	BSC	1.27	BSC		
J	0.008	0.015	0.21	0.38		
K	0.110	0.130	2.80	3.30		
L	0.295	0.305	7.50	7.74		
М	0°	10°	0°	10 °		
S	0.020	0.040	0.51	1.01		

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USA/EUROPE/Locations Not Listed: Motorola Literature Distribution; P.O. Box 5405, Denver, Colorado 80217. 303-675-2140 or 1-800-441-2447

Mfax™: RMFAX0@email.sps.mot.com - TOUCHTONE 602-244-6609 INTERNET: http://Design-NET.com

JAPAN: Nippon Motorola Ltd.; Tatsumi-SPD-JLDC, 6F Seibu-Butsuryu-Center, 3-14-2 Tatsumi Koto-Ku, Tokyo 135, Japan. 81-3-3521-8315

ASIA/PACIFIC: Motorola Semiconductors H.K. Ltd.; 8B Tai Ping Industrial Park, 51 Ting Kok Road, Tai Po, N.T., Hong Kong. 852-26629298



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