

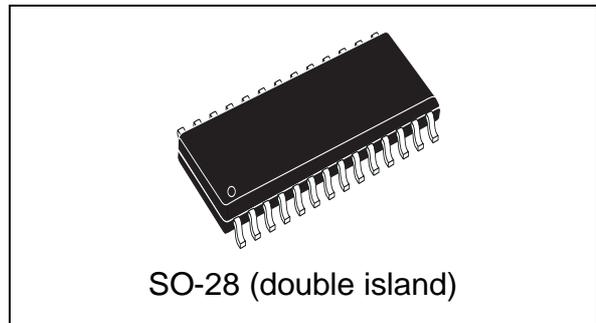
## Quad channel high-side driver

### Features

Type	$R_{DS(on)}$	$I_{OUT}$	$V_{CC}$
VNQ830P-E	65 m $\Omega$ <sup>(1)</sup>	6 A	36 V

1. Per each channel.

- ECOPACK<sup>®</sup>: lead free and RoHS compliant
- Automotive Grade: compliance with AEC guidelines
- Very low standby current
- CMOS compatible input
- On-state open-load detection
- Off-state open-load detection
- Thermal shutdown protection and diagnosis
- Undervoltage shutdown
- Overvoltage clamp
- Output stuck to  $V_{CC}$  detection
- Load current limitation
- Reverse battery protection
- Electrostatic discharge protection



### Description

The VNQ830P-E is a quad HSD formed by assembling two VND830P-E chips in the same SO-28 package. The VND830P-E is a monolithic device made using STMicroelectronics<sup>™</sup> VIPower<sup>™</sup> M0-3 technology. The VNQ830P-E is intended for driving any type of multiple load with one side connected to ground.

The active  $V_{CC}$  pin voltage clamp protects the device against low energy spikes (see ISO7637 transient compatibility table). Active current limitation combined with thermal shutdown and automatic restart protects the device against over-load. The device detects the open-load condition in both the on and off-state.

In the off-state the device detects if the output is shorted to  $V_{CC}$ . The device automatically turns off in the case where the ground pin becomes disconnected.

**Table 1. Device summary**

Package	Tube	Tape and reel
SO-28	VNQ830P-E	VNQ830PTR-E

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# 1 Block diagram and pin description

Figure 1. Block diagram

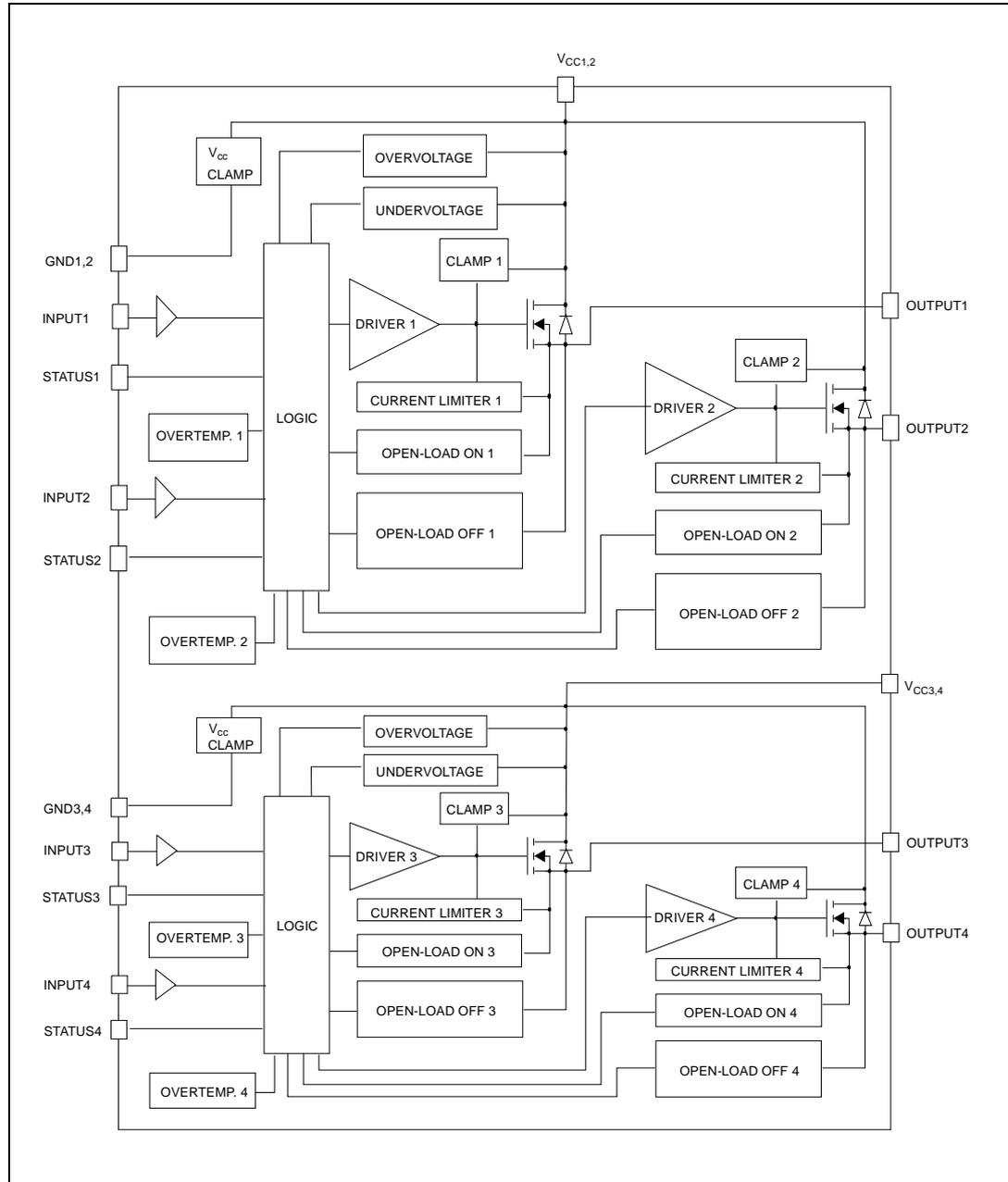


Figure 2. Configuration diagram (top view)

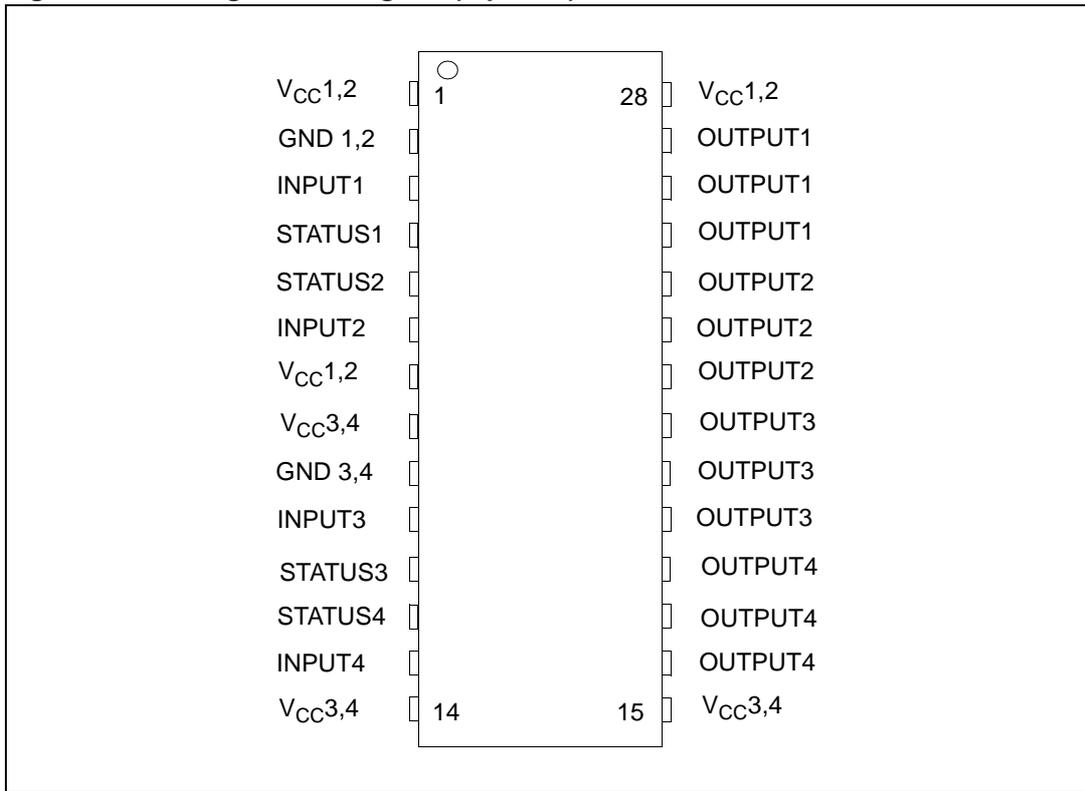


Table 2. Suggested connections for unused and not connected pins

Connection / pin	Status	N.C.	Output	Input
Floating	X	X	X	X
To ground		X		Through 10 KΩ resistor

## 2 Electrical specifications

### 2.1 Absolute maximum ratings

Stressing the device above the rating listed in [Table 3](#) may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability. Refer also to the STMicroelectronics SURE Program and other relevant quality document.

**Table 3. Absolute maximum ratings**

Symbol	Parameter	Value	Unit
$V_{CC}$	DC supply voltage	41	V
$-V_{CC}$	Reverse DC supply voltage	- 0.3	V
$-I_{GND}$	DC reverse ground pin current	- 200	mA
$I_{OUT}$	DC output current	Internally limited	A
$-I_{OUT}$	Reverse DC output current	- 6	A
$I_{IN}$	DC input current	+/- 10	mA
$I_{STAT}$	DC status current	+/- 10	mA
$V_{ESD}$	Electrostatic discharge (Human Body Model: R=1.5 K $\Omega$ ; C = 100 pF)		
	– INPUT	4000	V
	– STATUS	4000	V
	– OUTPUT	5000	V
	– $V_{CC}$	5000	V
$E_{MAX}$	Maximum switching energy (L = 1.5 mH; R <sub>L</sub> = 0 $\Omega$ ; V <sub>bat</sub> = 13.5 V; T <sub>jstart</sub> = 150 °C; I <sub>L</sub> = 9 A)	140	mJ
$P_{tot}$	Power dissipation (per island) at T <sub>lead</sub> = 25 °C	6.25	W
$T_j$	Junction operating temperature	Internally limited	°C
$T_{stg}$	Storage temperature	- 55 to 150	°C

## 2.2 Thermal data

**Table 4. Thermal data (per island)**

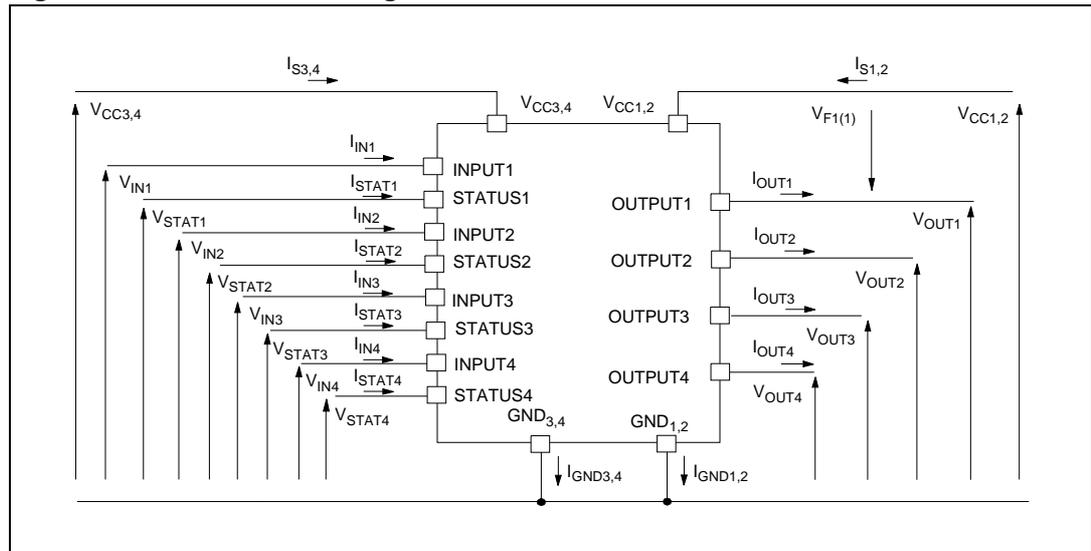
Symbol	Parameter	Value		Unit
$R_{thj-lead}$	Thermal resistance junction-lead	15		°C/W
$R_{thj-amb}$	Thermal resistance junction-ambient (one chip ON)	60 <sup>(1)</sup>	44 <sup>(2)</sup>	°C/W
$R_{thj-amb}$	Thermal resistance junction-ambient (two chips ON)	46 <sup>(1)</sup>	31 <sup>(2)</sup>	°C/W

1. When mounted on a standard single-sided FR-4 board with 0.5cm<sup>2</sup> of Cu (at least 35 μm thick) connected to all V<sub>CC</sub> pins. Horizontal mounting and no artificial air flow.
2. When mounted on a standard single-sided FR-4 board with 6cm<sup>2</sup> of Cu (at least 35 μm thick) connected to all V<sub>CC</sub> pins. Horizontal mounting and no artificial air flow.

## 2.3 Electrical characteristics

Values specified in this section are for 8 V < V<sub>CC</sub> < 36 V; -40°C < T<sub>j</sub> < 150°C, unless otherwise stated.

**Figure 3. Current and voltage conventions**



1.  $V_{Fn} = V_{CCn} - V_{OUTn}$  during reverse battery condition.

**Table 5. Power**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
V <sub>CC</sub>	Operating supply voltage		5.5	13	36	V
V <sub>USD</sub>	Undervoltage shutdown		3	4	5.5	V
V <sub>OV</sub>	Overshoot shutdown		36			V

Table 5. Power (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
R <sub>ON</sub>	On-state resistance	I <sub>OUT</sub> = 2 A; T <sub>j</sub> = 25°C			65	mΩ
		I <sub>OUT</sub> = 2 A; V <sub>CC</sub> > 8 V			130	mΩ
I <sub>S</sub>	Supply current	Off-state; V <sub>CC</sub> = 13 V; V <sub>IN</sub> = V <sub>OUT</sub> = 0 V		12	40	μA
		Off-state; V <sub>CC</sub> = 13 V; V <sub>IN</sub> = V <sub>OUT</sub> = 0 V; T <sub>j</sub> = 25°C		12	25	μA
		On-state; V <sub>CC</sub> = 13 V; V <sub>IN</sub> = 5 V; I <sub>OUT</sub> = 0 A		5	7	mA
I <sub>L(off1)</sub>	Off-state output current	V <sub>IN</sub> = V <sub>OUT</sub> = 0 V	0		50	μA
I <sub>L(off2)</sub>	Off-state output current	V <sub>IN</sub> = 0V; V <sub>OUT</sub> = 3.5 V	-75		0	μA
I <sub>L(off3)</sub>	Off-state output current	V <sub>IN</sub> = V <sub>OUT</sub> = 0V; V <sub>CC</sub> = 13 V; T <sub>j</sub> = 125°C			5	μA
I <sub>L(off4)</sub>	Off-state output current	V <sub>IN</sub> = V <sub>OUT</sub> = 0 V; V <sub>CC</sub> = 13 V; T <sub>j</sub> = 25°C			3	μA

Table 6. Protections

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
T <sub>TSD</sub>	Shutdown temperature		150	175	200	°C
T <sub>R</sub>	Reset temperature		135			°C
T <sub>hyst</sub>	Thermal hysteresis		7	15		°C
t <sub>SDL</sub>	Status delay in overload conditions	T <sub>j</sub> > T <sub>TSD</sub>			20	μs
I <sub>lim</sub>	Current limitation	V <sub>CC</sub> = 13 V	6	9	15	A
		5.5 V < V <sub>CC</sub> < 36 V			15	A
V <sub>demag</sub>	Turn-off output clamp voltage	I <sub>OUT</sub> = 2 A; L = 6 mH	V <sub>CC</sub> - 41	V <sub>CC</sub> - 48	V <sub>CC</sub> - 55	V

Note: To ensure long term reliability under heavy overload or short circuit conditions, protection and related diagnostic signals must be used together with a proper software strategy. If the device is subjected to abnormal conditions, this software must limit the duration and number of activation cycles.

Table 7. V<sub>CC</sub> - output diode

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
V <sub>F</sub>	Forward on voltage	- I <sub>OUT</sub> = 1.2 A; T <sub>j</sub> = 150°C	—	—	0.6	V

**Table 8. Switching ( $V_{CC} = 13V$ ;  $T_j = 25^\circ C$ )**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$t_{d(on)}$	Turn-on delay time	$R_L = 6.5\Omega$ from $V_{IN}$ rising edge to $V_{OUT} = 1.3 V$ (see <a href="#">Figure 5</a> )	—	30	—	$\mu s$
$t_{d(off)}$	Turn-off delay time	$R_L = 6.5\Omega$ from $V_{IN}$ falling edge to $V_{OUT} = 11.7 V$ (see <a href="#">Figure 5</a> )	—	30	—	$\mu s$
$dV_{OUT}/dt_{(on)}$	Turn-on voltage slope	$R_L = 6.5\Omega$ from $V_{OUT} = 1.3 V$ to $V_{OUT} = 10.4 V$ (see <a href="#">Figure 5</a> )	—	See <a href="#">Figure 10</a>	—	$V/\mu s$
$dV_{OUT}/dt_{(off)}$	Turn-off voltage slope	$R_L = 6.5\Omega$ from $V_{OUT} = 11.7 V$ to $V_{OUT} = 1.3 V$ (see <a href="#">Figure 5</a> )	—	See <a href="#">Figure 12</a>	—	$V/\mu s$

**Table 9. Logic inputs**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$V_{IL}$	Input low level				1.25	V
$I_{IL}$	Low level input current	$V_{IN} = 1.25 V$	1			$\mu A$
$V_{IH}$	Input high level		3.25			V
$I_{IH}$	High level input current	$V_{IN} = 3.25 V$			10	$\mu A$
$V_{I(hyst)}$	Input hysteresis voltage		0.5			V
$V_{ICL}$	Input clamp voltage	$I_{IN} = 1 mA$	6	6.8	8	V
		$I_{IN} = -1 mA$		-0.7		V

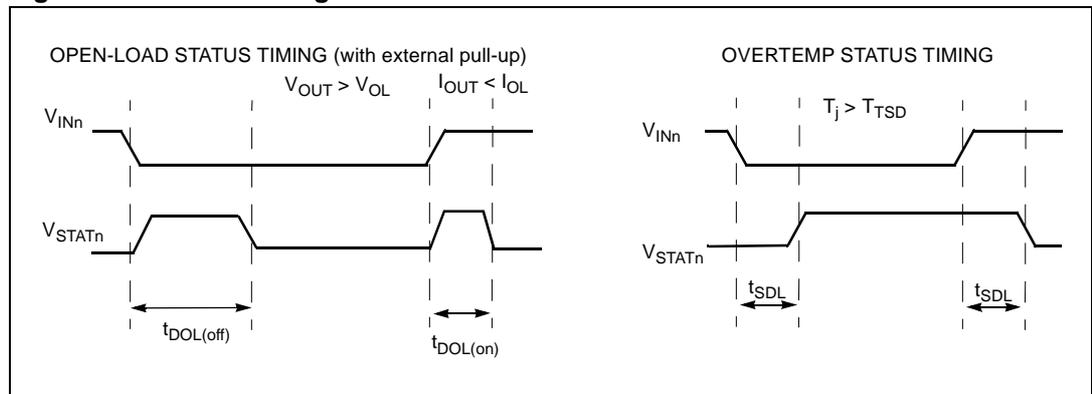
**Table 10. Status pin**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$V_{STAT}$	Status low output voltage	$I_{STAT} = 1.6 mA$			0.5	V
$I_{LSTAT}$	Status leakage current	Normal operation; $V_{STAT} = 5 V$			10	$\mu A$
$C_{STAT}$	Status pin input capacitance	Normal operation; $V_{STAT} = 5 V$			100	pF
$V_{SCL}$	Status clamp voltage	$I_{STAT} = 1 mA$	6	6.8	8	V
		$I_{STAT} = -1 mA$		-0.7		V

**Table 11. Open-load detection**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$I_{OL}$	Open-load on-state detection threshold	$V_{IN} = 5\text{ V}$	50	100	200	mA
$t_{DOL(on)}$	Open-load on-state detection delay	$I_{OUT} = 0\text{ A}$			200	$\mu\text{s}$
$V_{OL}$	Open-load off-state voltage detection threshold	$V_{IN} = 0\text{ V}$	1.5	2.5	3.5	V
$t_{DOL(off)}$	Open-load detection delay at turn-off				1000	$\mu\text{s}$

**Figure 4. Status timings**



**Figure 5. Switching characteristics**

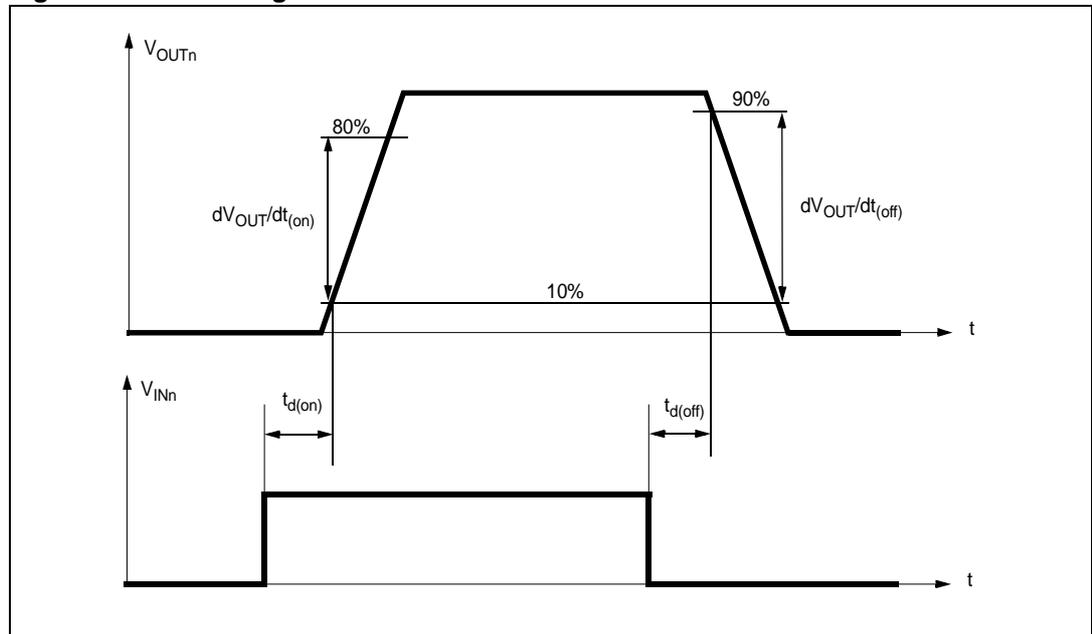


Table 12. Truth table

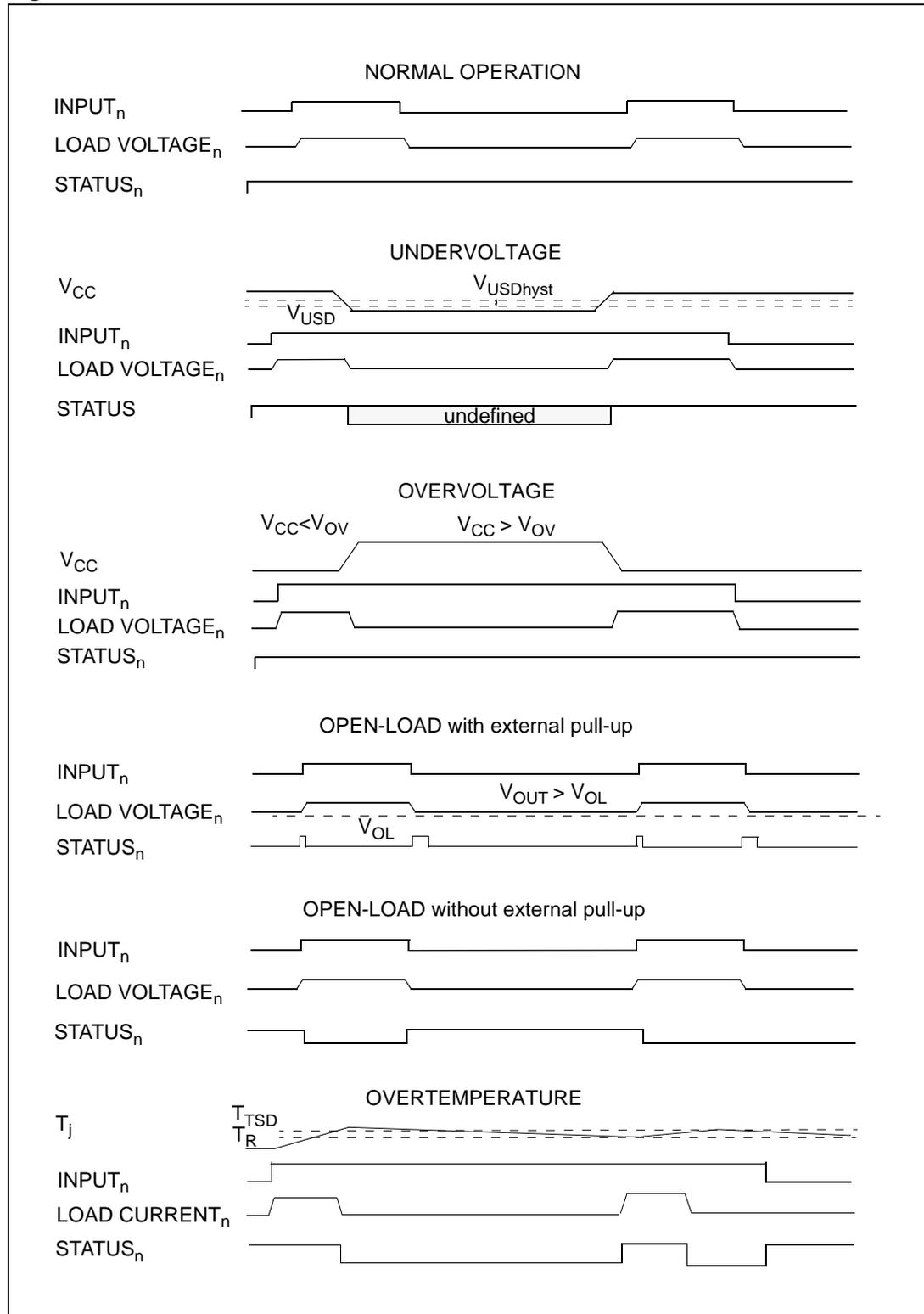
Conditions	Input	Output	Status
Normal operation	L	L	H
	H	H	H
Current limitation	L	L	H
	H	X	( $T_j < T_{TSD}$ ) H
	H	X	( $T_j > T_{TSD}$ ) L
Overtemperature	L	L	H
	H	L	L
Undervoltage	L	L	X
	H	L	X
Overvoltage	L	L	H
	H	L	H
Output voltage $> V_{OL}$	L	H	L
	H	H	H
Output current $< I_{OL}$	L	L	H
	H	H	L

Table 13. Electrical transient requirements

ISO T/R 7637/1 test pulse	Test level				Delays and impedance
	I	II	III	IV	
1	- 25 V <sup>(1)</sup>	- 50 V <sup>(1)</sup>	- 75 V <sup>(1)</sup>	- 100 V <sup>(1)</sup>	2 ms, 10 $\Omega$
2	+ 25 V <sup>(1)</sup>	+ 50 V <sup>(1)</sup>	+ 75 V <sup>(1)</sup>	+ 100 V <sup>(1)</sup>	0.2 ms, 10 $\Omega$
3a	- 25 V <sup>(1)</sup>	- 50 V <sup>(1)</sup>	- 100 V <sup>(1)</sup>	- 150 V <sup>(1)</sup>	0.1 $\mu$ s, 50 $\Omega$
3b	+ 25 V <sup>(1)</sup>	+ 50 V <sup>(1)</sup>	+ 75 V <sup>(1)</sup>	+ 100 V <sup>(1)</sup>	0.1 $\mu$ s, 50 $\Omega$
4	- 4 V <sup>(1)</sup>	- 5 V <sup>(1)</sup>	- 6 V <sup>(1)</sup>	- 7 V <sup>(1)</sup>	100 ms, 0.01 $\Omega$
5	+ 26.5 V <sup>(1)</sup>	+ 46.5 V <sup>(2)</sup>	+ 66.5 V <sup>(2)</sup>	+ 86.5 V <sup>(2)</sup>	400 ms, 2 $\Omega$

1. All functions of the device are performed as designed after exposure to disturbance.
2. One or more functions of the device is not performed as designed after exposure and cannot be returned to proper operation without replacing the device.

Figure 6. Waveforms



## 2.4 Electrical characteristics curves

Figure 7. Off-state output current

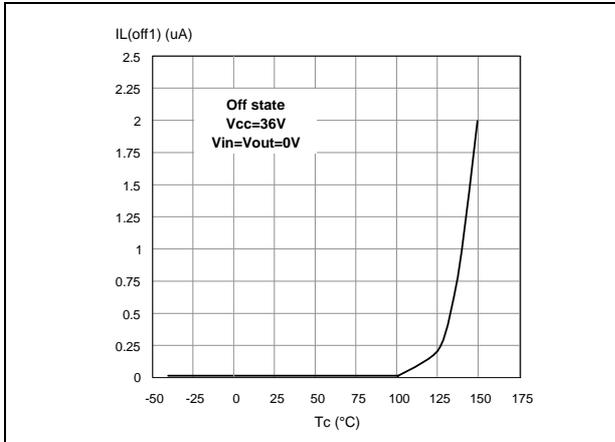


Figure 8. High level input current

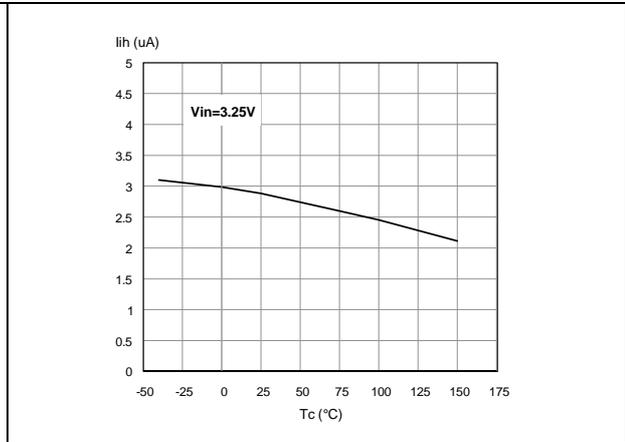


Figure 9. Input clamp voltage

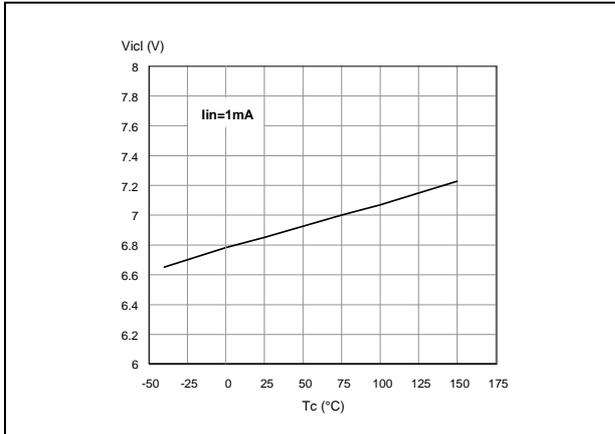


Figure 10. Turn-on voltage slope

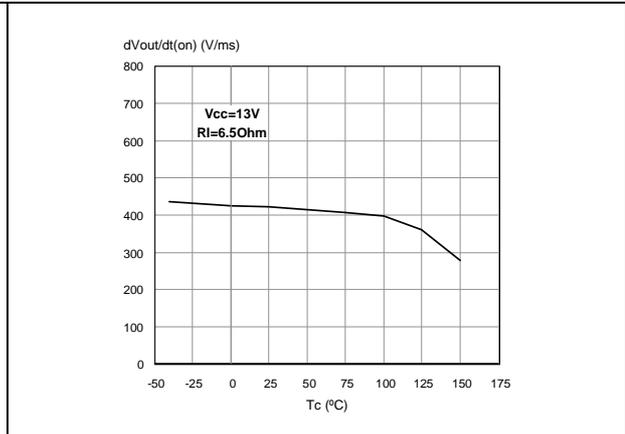


Figure 11. Overvoltage shutdown

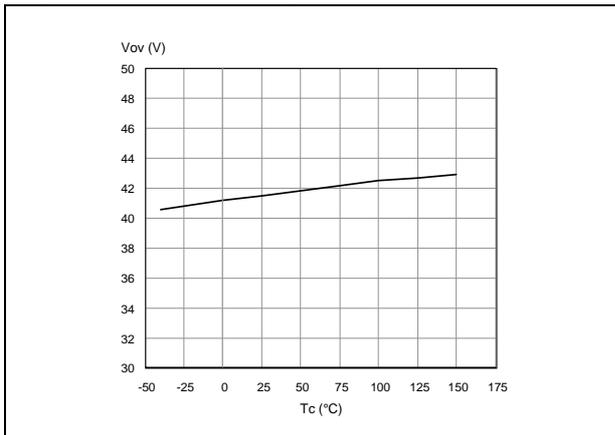


Figure 12. Turn-off voltage slope

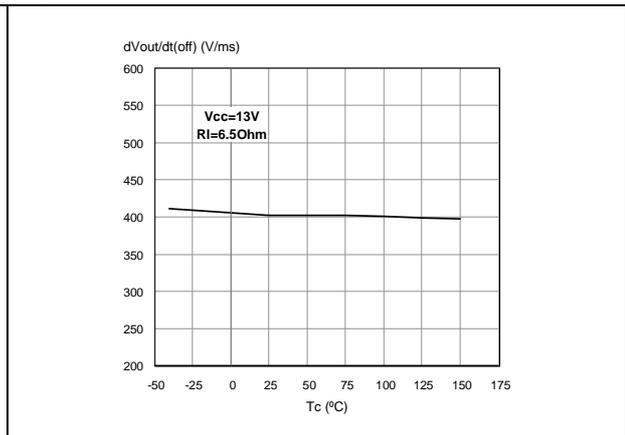


Figure 13.  $I_{LIM}$  vs  $T_{case}$

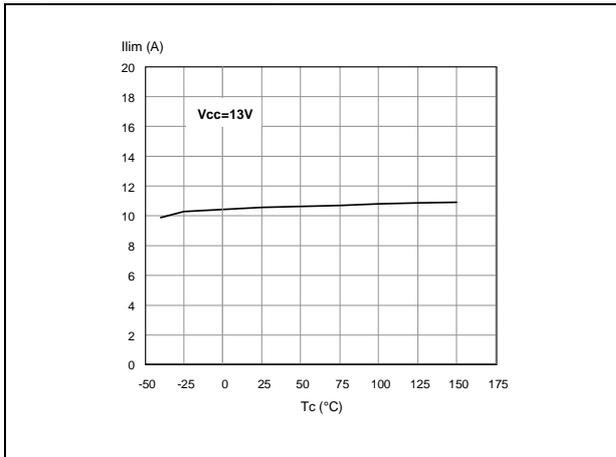


Figure 14. On-state resistance vs  $V_{CC}$

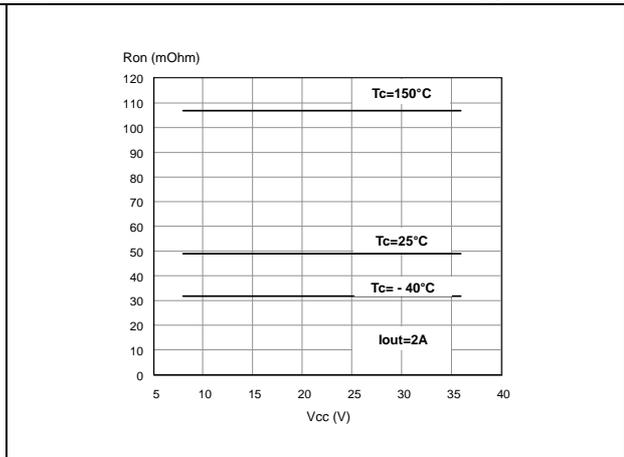


Figure 15. Input high level

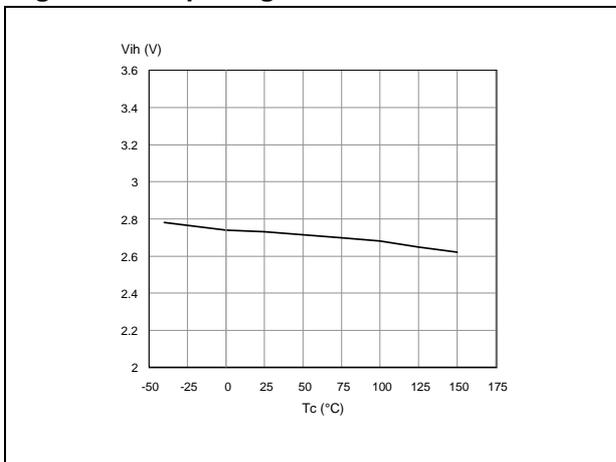


Figure 16. Input hysteresis voltage

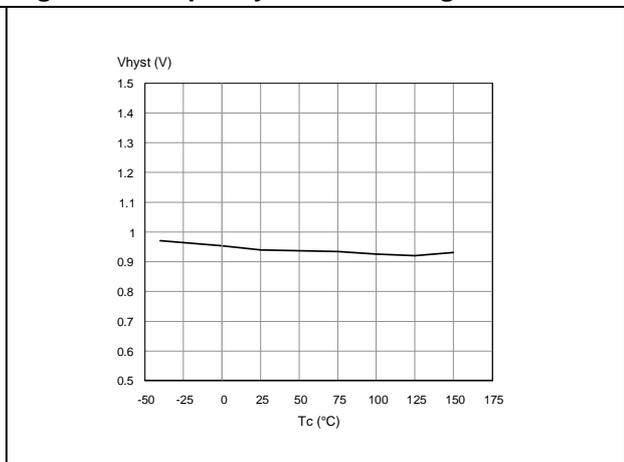


Figure 17. On-state resistance vs  $T_{case}$

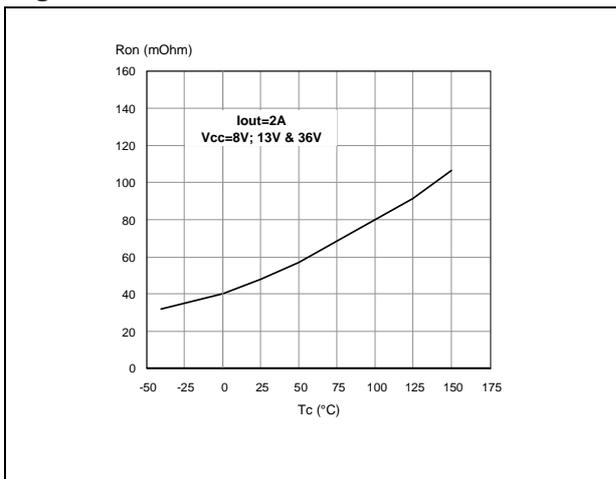


Figure 18. Input low level

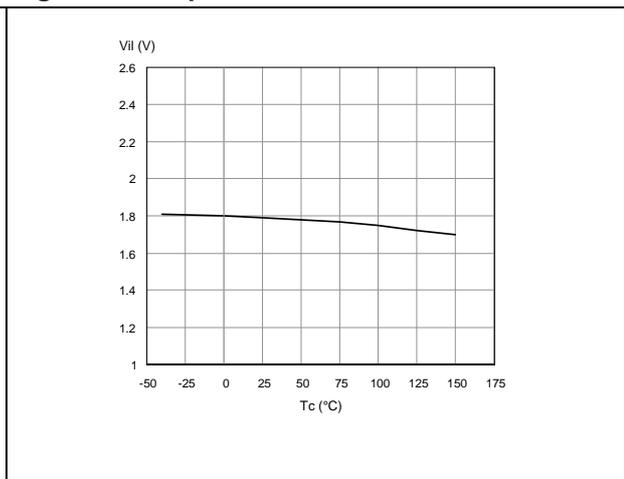


Figure 19. Status leakage current

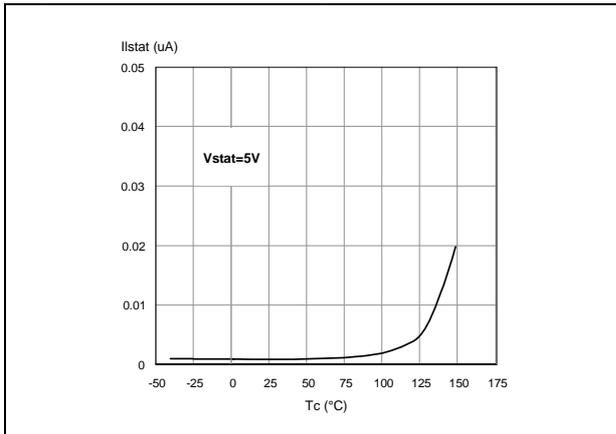


Figure 20. Status low output voltage

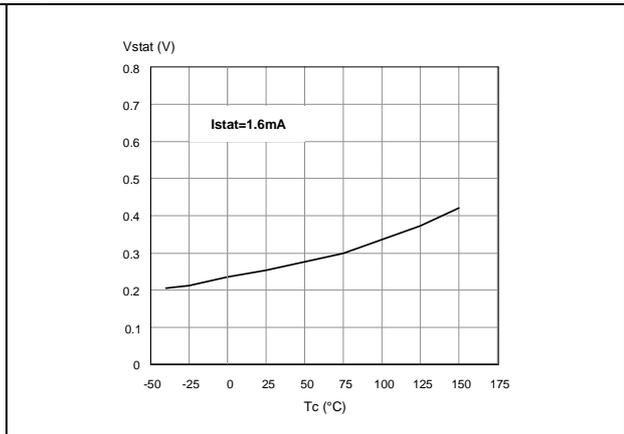


Figure 21. Status clamp voltage

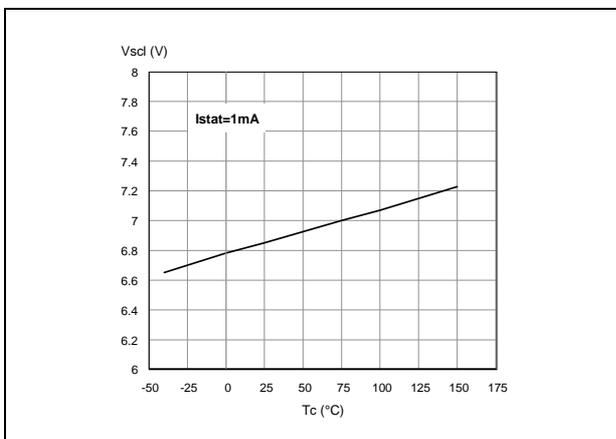


Figure 22. Open-load on-state detection threshold

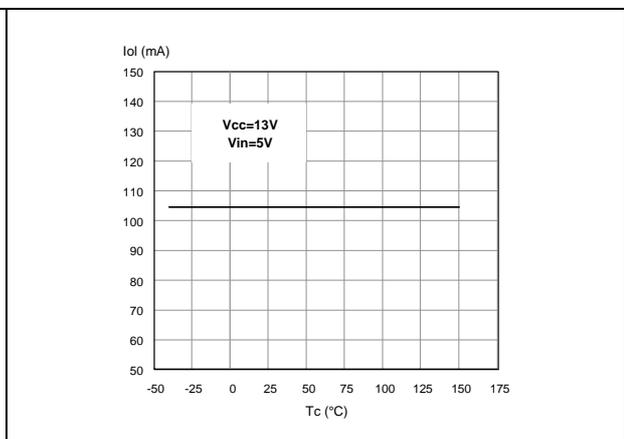
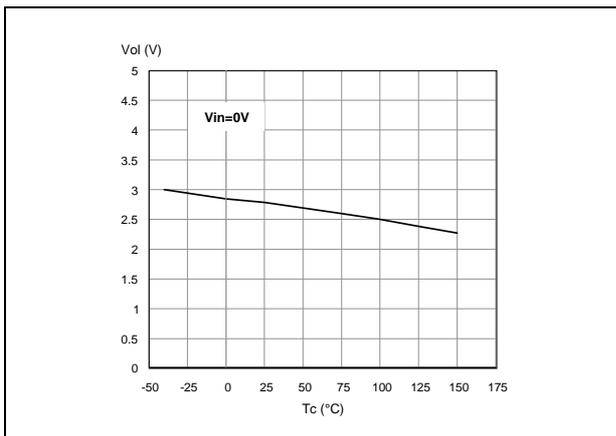
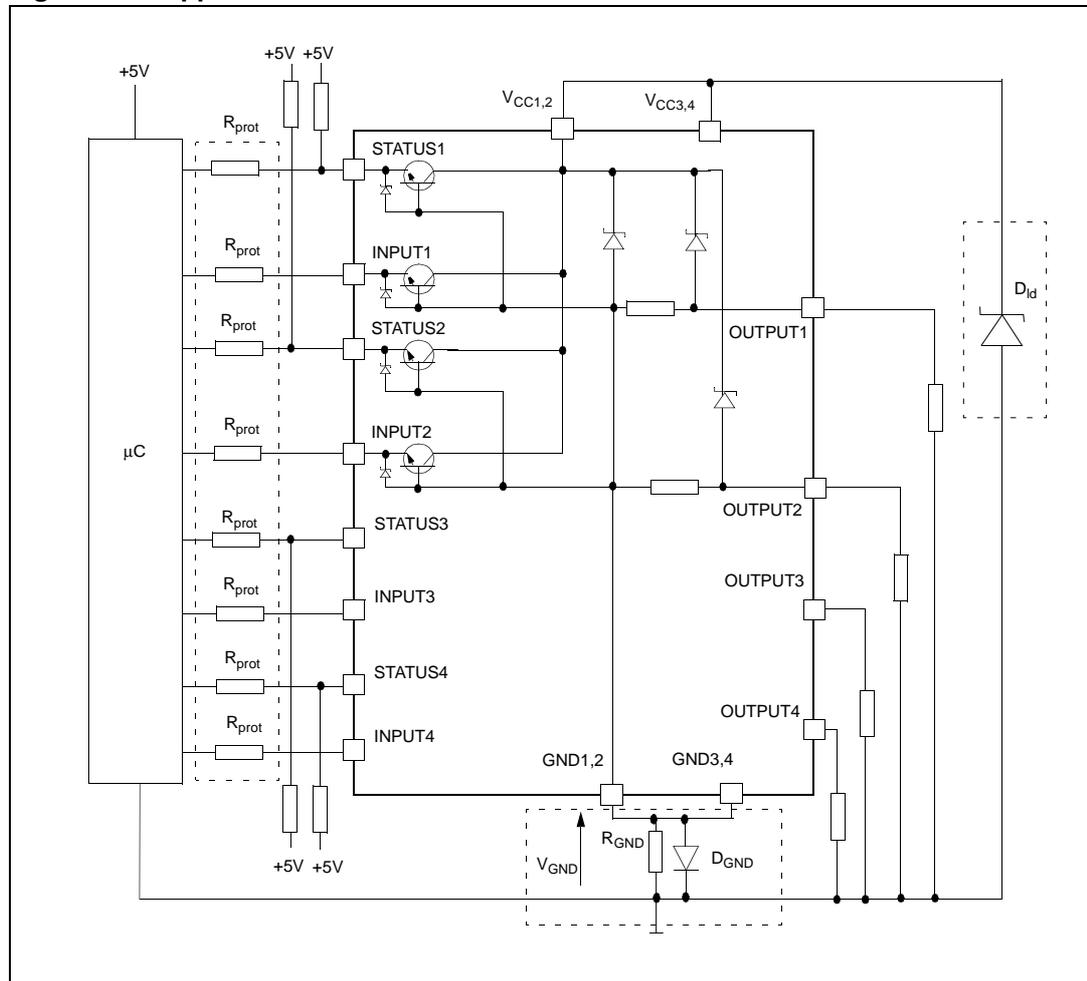


Figure 23. Open-load off-state voltage detection threshold



### 3 Application information

Figure 24. Application schematic



Note: Channels 3 & 4 have the same internal circuit as channel 1 & 2.

#### 3.1 GND protection network against reverse battery

This section provides two solutions for implementing a ground protection network against reverse battery.

##### 3.1.1 Solution 1: a resistor in the ground line (R<sub>GND</sub> only)

This can be used with any type of load.

The following show how to dimension the R<sub>GND</sub> resistor:

1.  $R_{GND} \leq 600 \text{ mV} / 2 (I_{S(on)max})$
2.  $R_{GND} \geq (-V_{CC}) / (-I_{GND})$

where  $-I_{GND}$  is the DC reverse ground pin current and can be found in the absolute maximum rating section of the device datasheet.

Power dissipation in  $R_{GND}$  (when  $V_{CC} < 0$  during reverse battery situations) is:

$$P_D = (-V_{CC})^2 / R_{GND}$$

This resistor can be shared amongst several different HSDs. Please note that the value of this resistor should be calculated with formula (1) where  $I_{S(on)max}$  becomes the sum of the maximum on-state currents of the different devices.

Please note that, if the microprocessor ground is not shared by the device ground, then the  $R_{GND}$  produces a shift ( $I_{S(on)max} * R_{GND}$ ) in the input thresholds and the status output values. This shift varies depending on how many devices are ON in the case of several high-side drivers sharing the same  $R_{GND}$ .

If the calculated power dissipation requires the use of a large resistor, or several devices have to share the same resistor, then ST suggests using solution 2 below.

### 3.1.2 Solution 2: a diode ( $D_{GND}$ ) in the ground line

A resistor ( $R_{GND} = 1 \text{ k}\Omega$ ) should be inserted in parallel to  $D_{GND}$  if the device is driving an inductive load. This small signal diode can be safely shared amongst several different HSD. Also in this case, the presence of the ground network produces a shift ( $\sim 600\text{mV}$ ) in the input threshold and the status output values if the microprocessor ground is not common with the device ground. This shift not varies if more than one HSD shares the same diode/resistor network. Series resistor in INPUT and STATUS lines are also required to prevent that, during battery voltage transient, the current exceeds the Absolute Maximum Rating. Safest configuration for unused INPUT and STATUS pin is to leave them unconnected.

## 3.2 Load dump protection

$D_{ld}$  is necessary (voltage transient suppressor) if the load dump peak voltage exceeds the  $V_{CC}$  maximum DC rating. The same applies if the device is subject to transients on the  $V_{CC}$  line that are greater than those shown in [Table 13](#).

## 3.3 MCU I/O protection

If a ground protection network is used and negative transients are present on the  $V_{CC}$  line, the control pins are pulled negative. ST suggests to insert a resistor ( $R_{prot}$ ) in line to prevent the microcontroller I/O pins from latching up.

The value of these resistors is a compromise between the leakage current of microcontroller and the current required by the HSD I/Os (Input levels compatibility) with the latch-up limit of microcontroller I/Os:

$$-V_{CCpeak} / I_{latchup} \leq R_{prot} \leq (V_{OH\mu C} - V_{IH} - V_{GND}) / I_{IHmax}$$

**Example**

For the following conditions:

$$V_{CCpeak} = - 100 \text{ V}$$

$$I_{latchup} \geq 20 \text{ mA}$$

$$V_{OH\mu C} \geq 4.5 \text{ V}$$

$$5 \text{ k}\Omega \leq R_{prot} \leq 65 \text{ k}\Omega.$$

Recommended values are:

$$R_{prot} = 10 \text{ k}\Omega$$

**3.4 Open-load detection in off-state**

Off-state open-load detection requires an external pull-up resistor ( $R_{PU}$ ) connected between OUTPUT pin and a positive supply voltage ( $V_{PU}$ ) like the +5V line used to supply the microprocessor.

The external resistor has to be selected according to the following requirements:

1. No false open load indication when load is connected: in this case we have to avoid  $V_{OUT}$  to be higher than  $V_{OLmin}$ ; this results in the following condition:

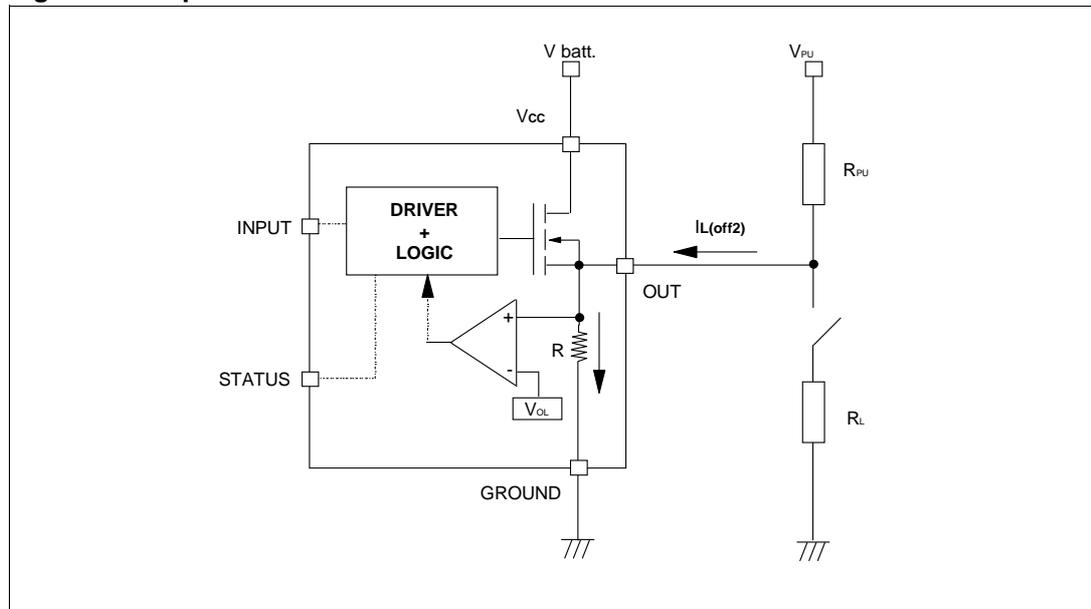
$$V_{OUT} = (V_{PU} / (R_L + R_{PU}))R_L < V_{OLmin}.$$

2. No misdetection when load is disconnected: in this case the  $V_{OUT}$  has to be higher than  $V_{OLmax}$ ; this results in the following condition:

$$R_{PU} < (V_{PU} - V_{OLmax}) / I_{L(off2)}.$$

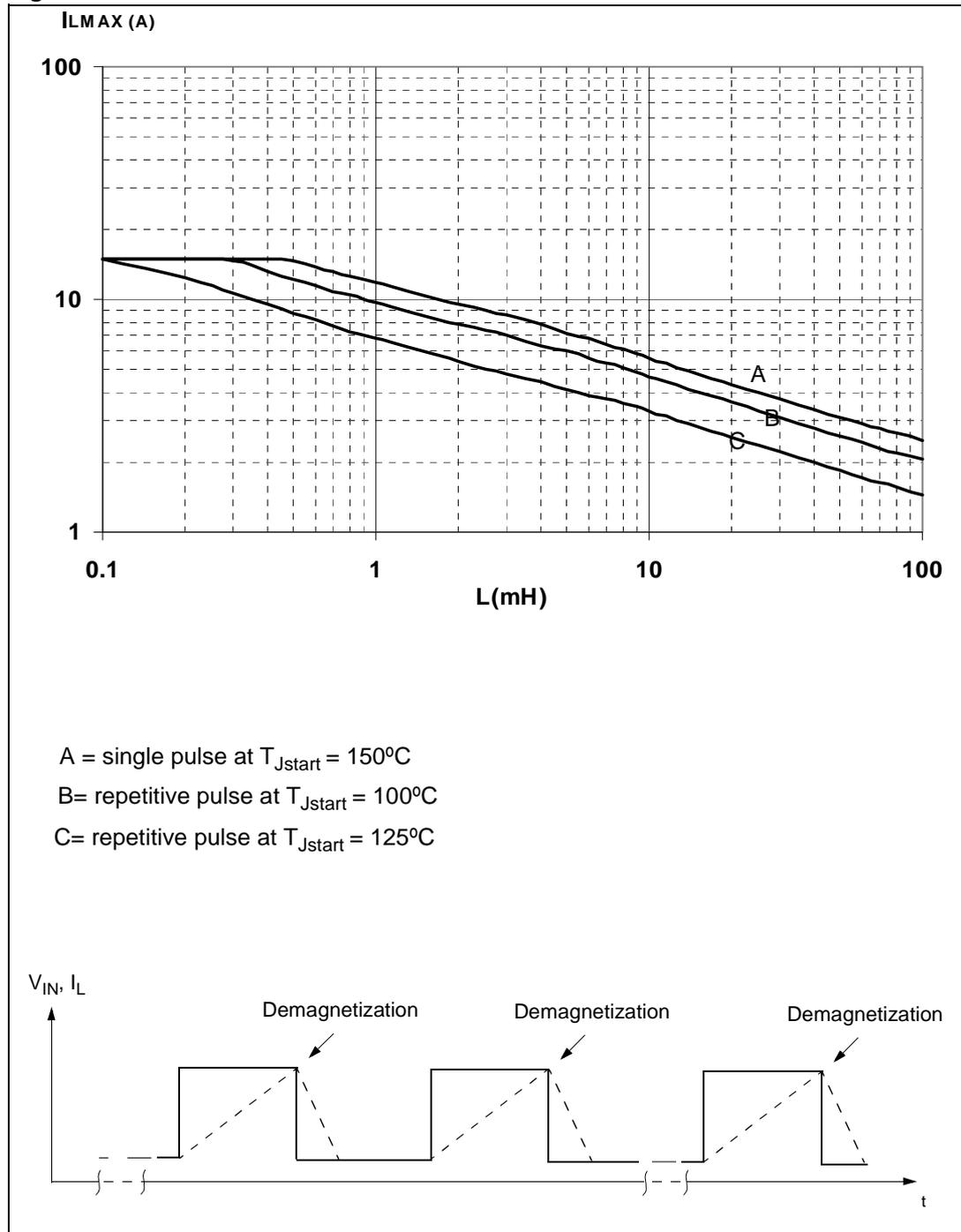
Because  $I_{S(OFF)}$  may significantly increase if  $V_{out}$  is pulled high (up to several mA), the pull-up resistor  $R_{PU}$  should be connected to a supply that is switched OFF when the module is in standby.

**Figure 25. Open-load detection in off-state**



### 3.5 Maximum demagnetization energy ( $V_{CC} = 13.5\text{ V}$ )

Figure 26. Maximum turn-off current versus load inductance

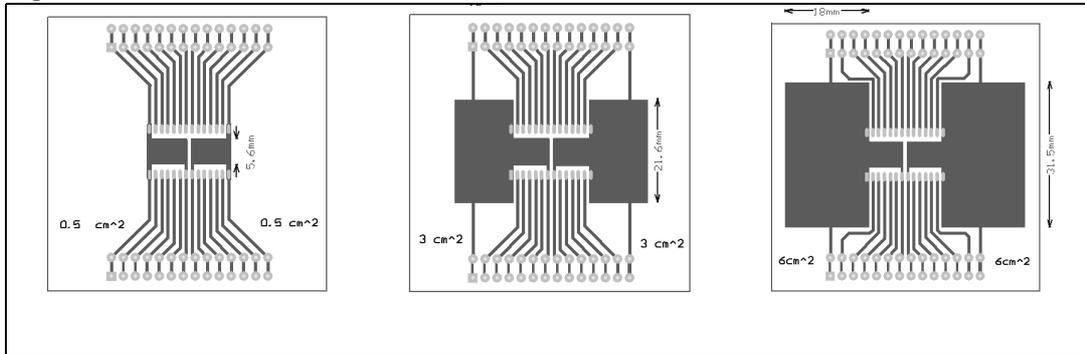


Note: Values are generated with  $R_L = 0\ \Omega$ .  
 In case of repetitive pulses,  $T_{Jstart}$  (at beginning of each demagnetization) of every pulse must not exceed the temperature specified above for curves B and C.

## 4 Package and PCB thermal data

### 4.1 SO-28 thermal data

Figure 27. SO-28 PC board



Note: Layout condition of  $R_{th}$  and  $Z_{th}$  measurements (PCB FR4 area = 58 mm x 58 mm, PCB thickness = 2 mm, Cu thickness = 35  $\mu$ m, Copper areas: 0.5 cm<sup>2</sup>, 3 cm<sup>2</sup>, 6 cm<sup>2</sup>).

Table 14. Thermal calculation according to the PCB heatsink area

Chip 1	Chip 2	$T_{jchip1}$	$T_{jchip2}$	Note
ON	OFF	$R_{thA} \times P_{dchip1} + T_{amb}$	$R_{thC} \times P_{dchip1} + T_{amb}$	
OFF	ON	$R_{thC} \times P_{dchip2} + T_{amb}$	$R_{thA} \times P_{dchip2} + T_{amb}$	
ON	ON	$R_{thB} \times (P_{dchip1} + P_{dchip2}) + T_{amb}$	$R_{thB} \times (P_{dchip1} + P_{dchip2}) + T_{amb}$	$P_{dchip1} = P_{dchip2}$
ON	ON	$(R_{thA} \times P_{dchip1}) + R_{thC} \times P_{dchip2} + T_{amb}$	$(R_{thA} \times P_{dchip2}) + R_{thC} \times P_{dchip1} + T_{amb}$	$P_{dchip1} \neq P_{dchip2}$

$R_{thA}$  = thermal resistance junction to ambient with one chip ON

$R_{thB}$  = thermal resistance junction to ambient with both chips ON and  $P_{dchip1} = P_{dchip2}$

$R_{thC}$  = mutual thermal resistance

Figure 28.  $R_{thj-amb}$  vs PCB copper area in open box free air condition

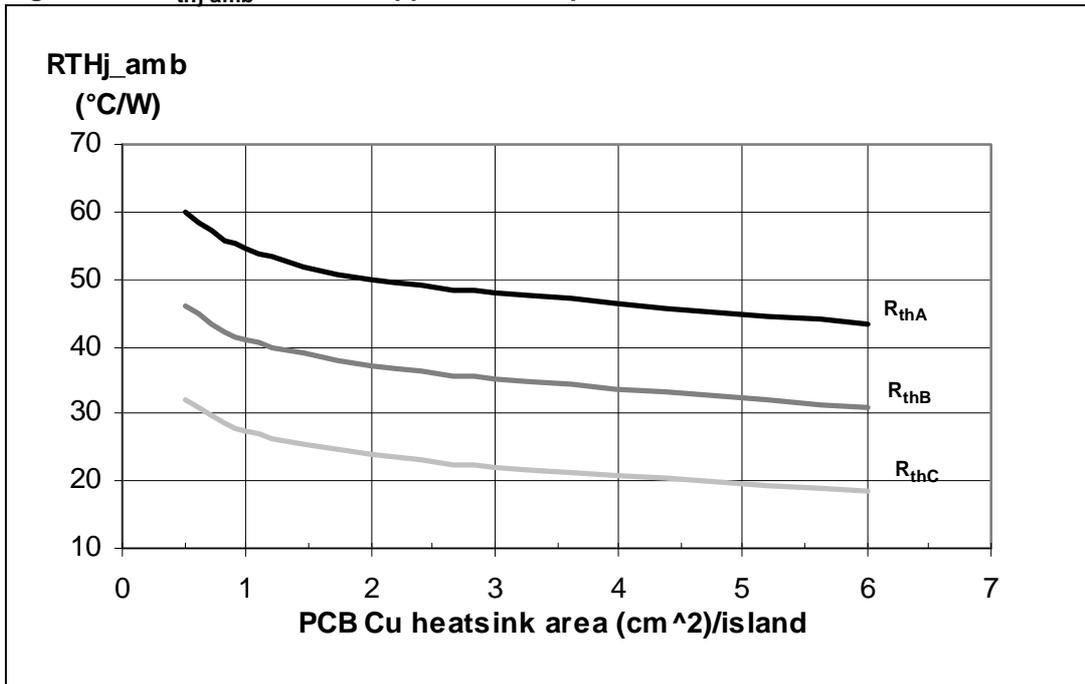
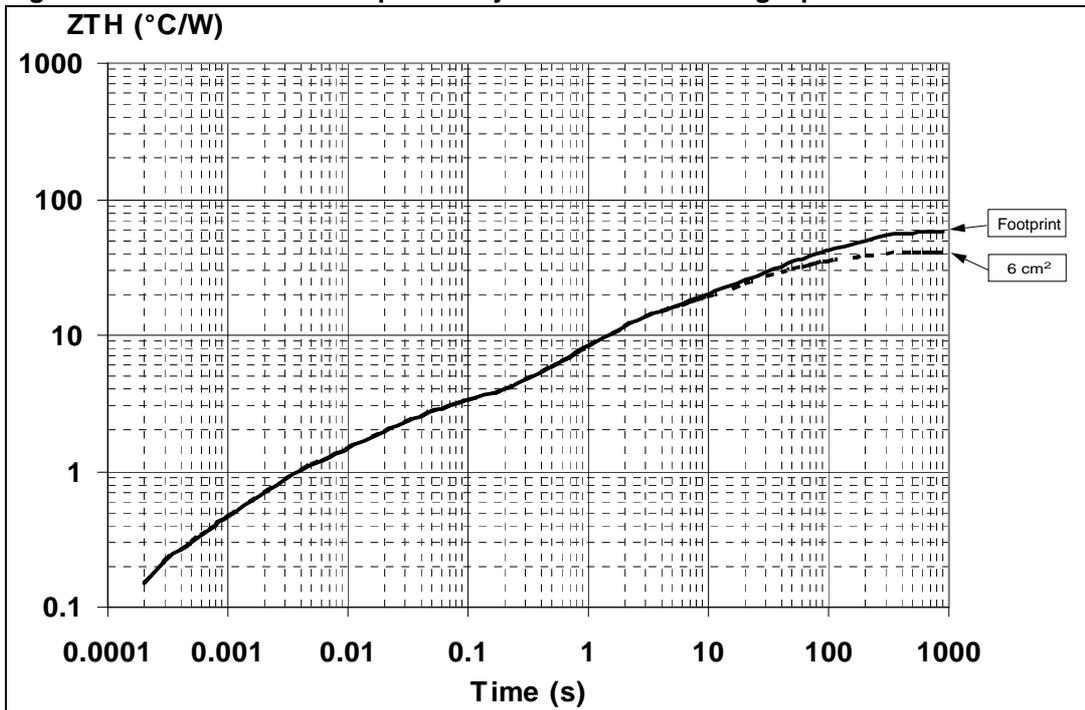


Figure 29. SO-28 thermal impedance junction ambient single pulse



Equation 1: pulse calculation formula

$$Z_{TH\delta} = R_{TH} \cdot \delta + Z_{THtp}(1 - \delta)$$

where  $\delta = t_p/T$

Figure 30. Thermal fitting model of a quad channel HSD in SO-28

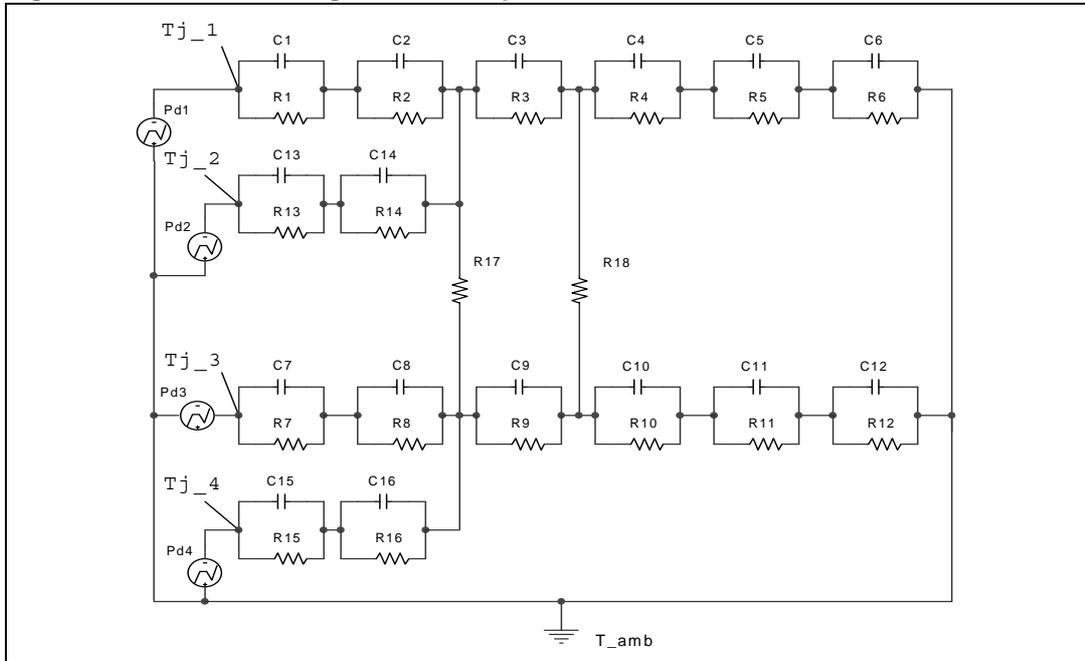


Table 15. Thermal parameters

Area / island (cm <sup>2</sup> )	Footprint	6
R1 = R7 = R13 = R15 (°C/W)	0.15	
R2 = R8 = R14 = R16 (°C/W)	0.7	
R3 = R9 (°C/W)	1.8	
R4 = R10 (°C/W)	10	
R5 = R11 (°C/W)	15	
R6 = R12 (°C/W)	30	13
C1 = C7 = C13 = C15 (W.s/°C)	0.0005	
C2 = C8 = C14 = C16 (W.s/°C)	3E-03	
C3 = C9 (W.s/°C)	1.50E-02	
C4 = C10 (W.s/°C)	0.15	
C5 = C11 (W.s/°C)	1.5	
C6 = C12 (W.s/°C)	5	8
R17 = R18 (°C/W)	150	

## 5 Package and packing information

### 5.1 ECOPACK® packages

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: [www.st.com](http://www.st.com). ECOPACK® is an ST trademark.

Figure 31. SO-28 package dimensions

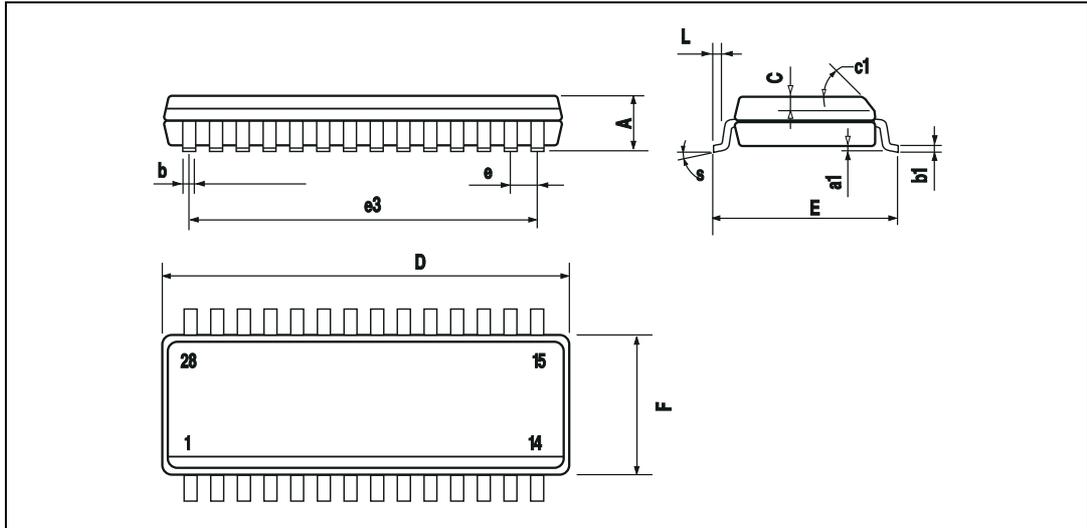


Table 16. SO-28 mechanical data

Symbol	Millimeters		
	Min.	Typ.	Max.
A			2.65
a1	0.10		0.30
b	0.35		0.49
b1	0.23		0.32
C		0.50	
c1	45° (typ.)		
D	17.7		18.1
E	10.00		10.65
e		1.27	
e3		16.51	
F	7.40		7.60
L	0.40		1.27
S	8° (max.)		

## 5.2 SO-28 packing information

Figure 32. SO-28 tube shipment (no suffix)

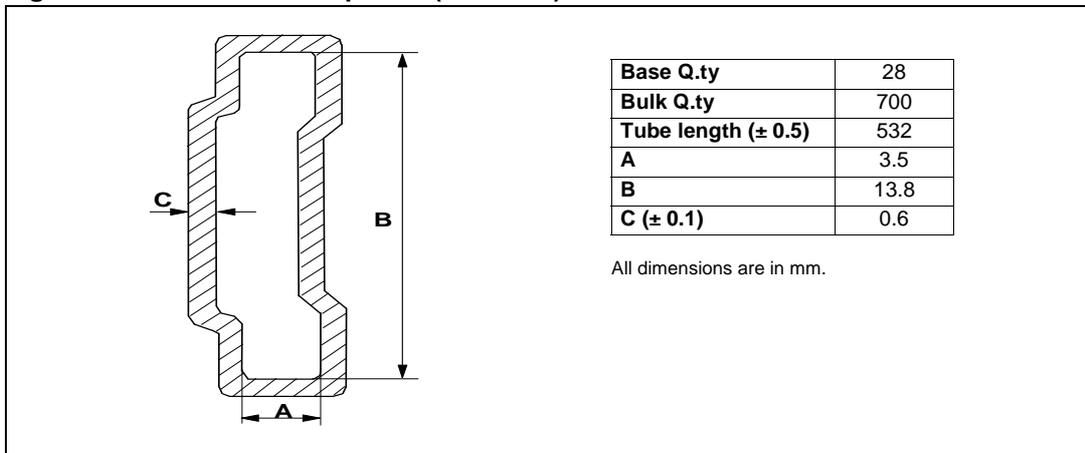
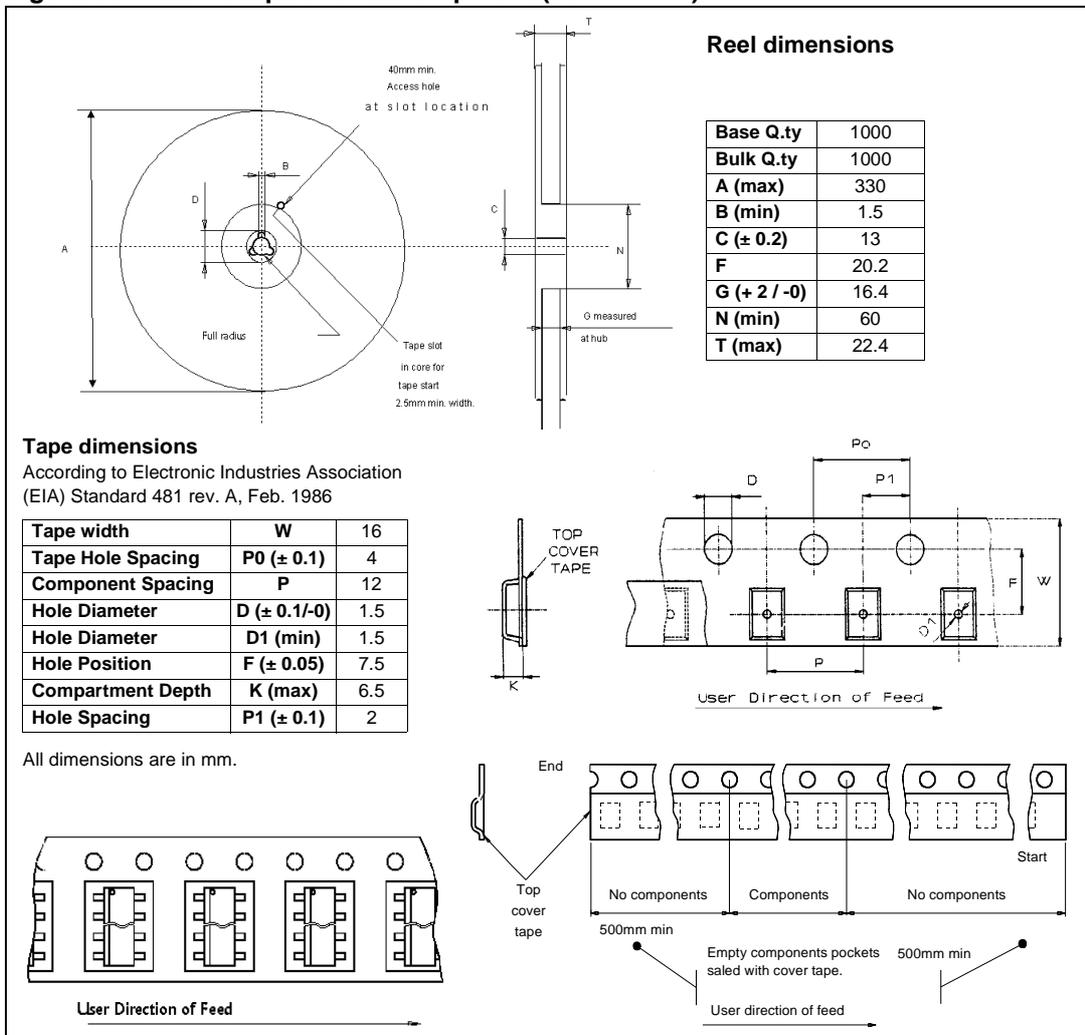


Figure 33. SO-28 tape and reel shipment (suffix "TR")



## 6 Revision history

Table 17. Document revision history

Date	Revision	Changes
03-May-2006	1	Initial release.
18-Dec-2008	2	Document reformatted and restructured. Added contents, list of tables and figures. Added <i>ECOPACK<sup>®</sup> packages</i> information.
03-May-2010	3	Changed <i>Features</i> list. Replaced VND830P-E to VND830-E.
07-Feb-2011	4	<i>Table 3: Absolute maximum ratings</i> – E <sub>MAX</sub> : updated value Updated <i>Figure 5: Switching characteristics</i> Updated <i>Table 15: Thermal parameters</i>
19-Sep-2013	5	Updated Disclaimer.

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